



# NOSTROMO Project

NEXT-GENERATION OPEN-SOURCE TOOLS FOR ATM PERFORMANCE MODELLING AND OPTIMISATION

03/09/2021 – Engage KTN Workshop  
TC2 ‘Machine Learning, AI and automation in ATM’

NOSTROMO Project Leader, <Mayte Cano (CRIDA)>

NOSTROMO WP3 Leader, <Francisco Camara (DTU)>



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## Introduction to NOSTROMO Project

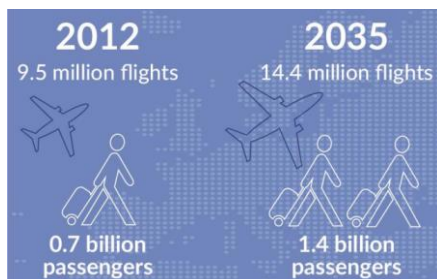
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# SESAR Programme: ATM MP







## Performance Ambitions



SESAR: A performance-driven programme

Technological pillar of SES



Key performance area	SES High-Level Goals vs. 2005	Key performance indicator	SESAR ambition vs. baseline 2012	
			Absolute saving	Relative saving
 <b>Cost efficiency: ANS productivity</b>	Reduce ATM services unit cost by 50% or more	<ul style="list-style-type: none"> <li>Gate-to-gate direct ANS cost per flight</li> <li>- Determined unit cost for en-route ANS*</li> <li>- Determined unit cost for terminal ANS*</li> </ul>	EUR 290-380	30-40%
 <b>Operational efficiency</b>	-	<ul style="list-style-type: none"> <li>Fuel burn per flight (tonne/flight)</li> <li>Flight time per flight (min/flight)</li> </ul>	4-8 min 0.25-0.5 tonne	3-6 % 5-10 %
 <b>Capacity</b>	Enable 3-fold increase in ATM capacity	<ul style="list-style-type: none"> <li>Departure delay (min/dep)</li> <li>- En-route air traffic flow management delay*</li> <li>- Primary and reactionary delays all causes</li> <li>Additional flights at congested airports (million)</li> <li>Network throughput additional flights (million)</li> </ul>	1-3 min  0.2-0.4 (million) 7.6-9.5 (million) <small>Additional flights, not saving</small>	10-30 %  5-10 % <sup>1</sup> 80-100 % <sup>2</sup>
 <b>Environment</b>	Enable 10 % reduction in the effects flights have on the environment	<ul style="list-style-type: none"> <li>CO<sub>2</sub> emissions (tonne/flight)</li> <li>- Horizontal flight efficiency (actual trajectory)*</li> <li>- Vertical efficiency</li> <li>- Taxi-out phase</li> </ul>	0.79-1.6 tonne	5-10 %
 <b>Safety</b>	Improve safety by factor 10	<ul style="list-style-type: none"> <li>Accidents with ATM contribution</li> </ul>	No increase in accidents	Improvement by a factor 3-4
 <b>Security</b>	-	<ul style="list-style-type: none"> <li>ATM related security incidents resulting in traffic disruptions</li> </ul>	No increase in incidents	

\* Targeted by the Performance Scheme

<sup>1</sup> Additional flights that can be accommodated at congested airports, representing 5-10 % of flights at congested airports (~31 % of 14.4 (million) flights in 2035).

<sup>2</sup> Additional traffic accommodated in 2035 in comparison with 2012 and associated with ANSP productivity gains, enabled by SESAR. Note: Numbers are rounded.

Metrics with monetary value in business view

# Why do we need Performance Assessment?



How can be known that a SESAR Solution will bring the expected benefits?

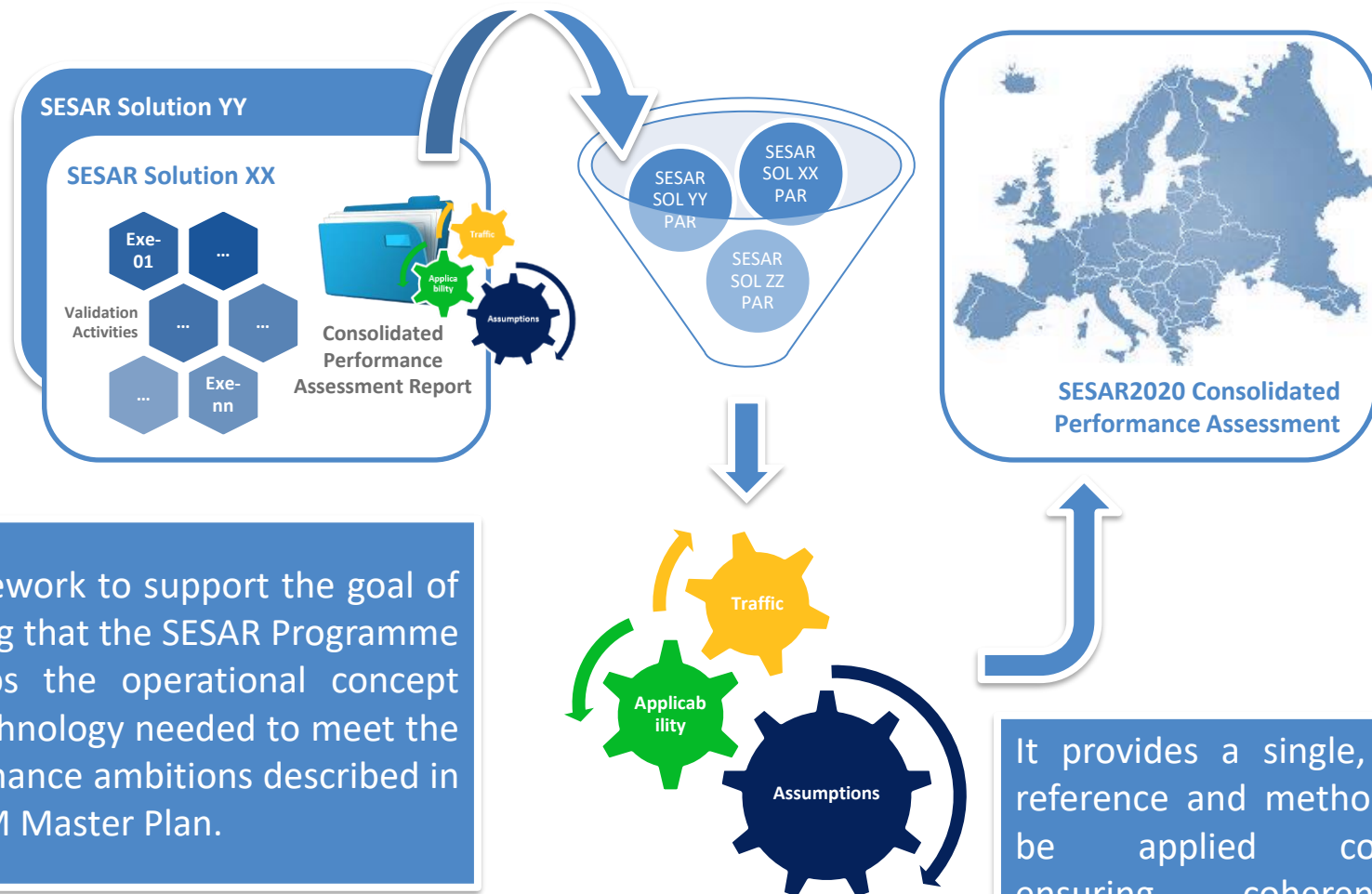


How can be justified that a SESAR Solution is ready for deployment and industrialisation?



How can be known if it is necessary to plan additional assessments or propose new concepts?

# SESAR Performance Framework



# NOSTROMO Project: The Challenge

## Macroscopic Models

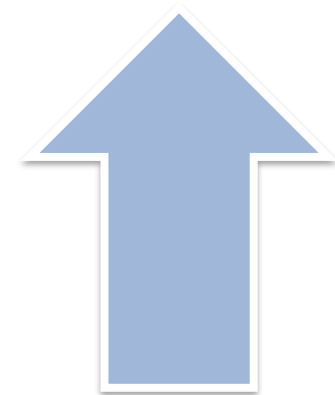


- + Easy to compute
- + Easy to explain and communicate results to decision makers
- No results on network effects
- Supported by expert judgement (no empirical evidence)



+ Realistic model of ATM components' behaviours and their interrelations due to new solutions

- High computational costs
- Complex results analysis and communication



## Microscopic Models

Evaluation of the impact of new ATM concepts and technologies at a system-wide level

# NOSTROMO Project: Objectives

NOSTROMO project aims to develop, demonstrate and evaluate an innovative modelling approach for the assessment of the performance impact of future ATM concepts and solutions at ECAC network level, providing both a realistic representation of ATM system and model transparency, computational tractability and ease of use.



**Develop a methodology** for the construction of ATM performance metamodels, by exploiting recent advances in the field of active learning.



**Implement the proposed metamodeling methodology** by developing Open-Source metamodels of two state-of-the-art microsimulation tools (Mercury and FLITAN) able to reproduce ATM performance at ECAC level.

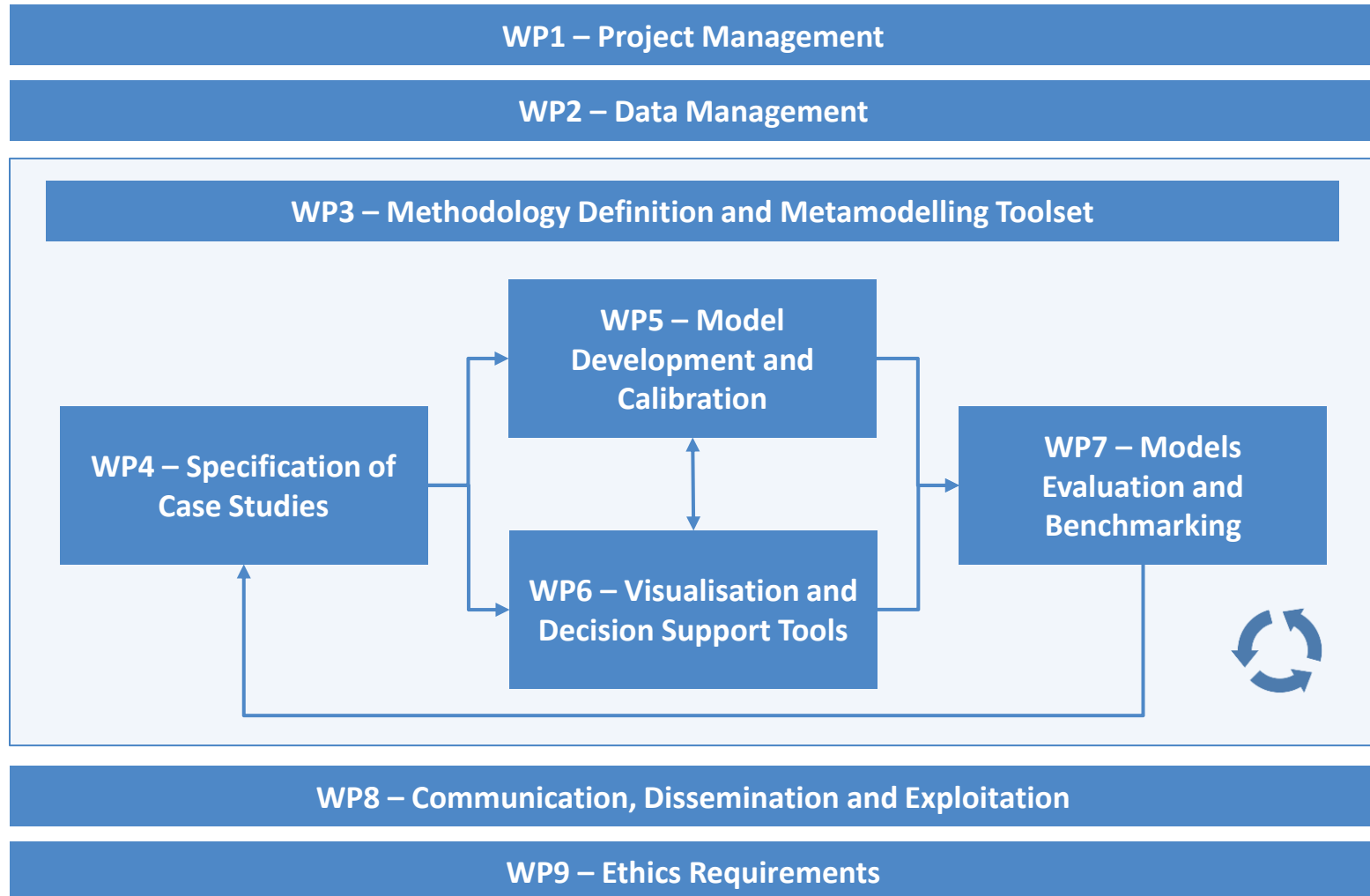


**Develop a set of visualization and visual analytics tools** that facilitate the analysis, interpretation and communication of the results of the new performance metamodels.



**Demonstrate and evaluate the maturity of the NOSTROMO approach** and the capabilities of the newly developed toolset through a set of case studies.

# NOSTROMO Project: Work Breakdown Structure





# NOSTROMO Project: Consortium



Performing validation activities (WP7)



Definition of visualisation and visual analytics tools (WP2 & 6)



Development of micro-models (WP5)



Application of e-OCVM (WP4)

Technical University of Denmark

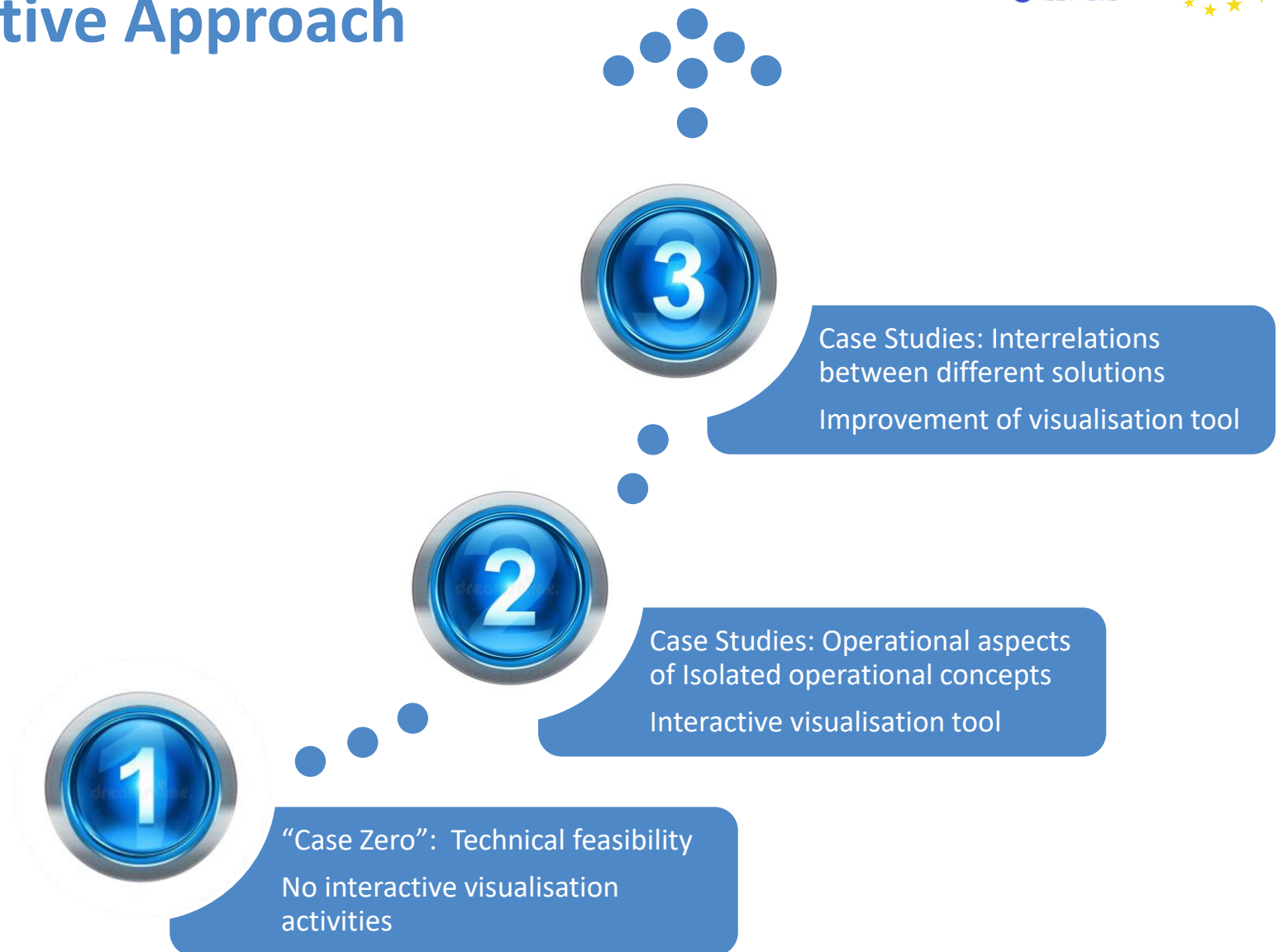


Application of active learning Metamodelling techniques (WP3)



Development of micro-models

# NOSTROMO Project: Incremental and Iterative Approach





## Proposed Case Studies

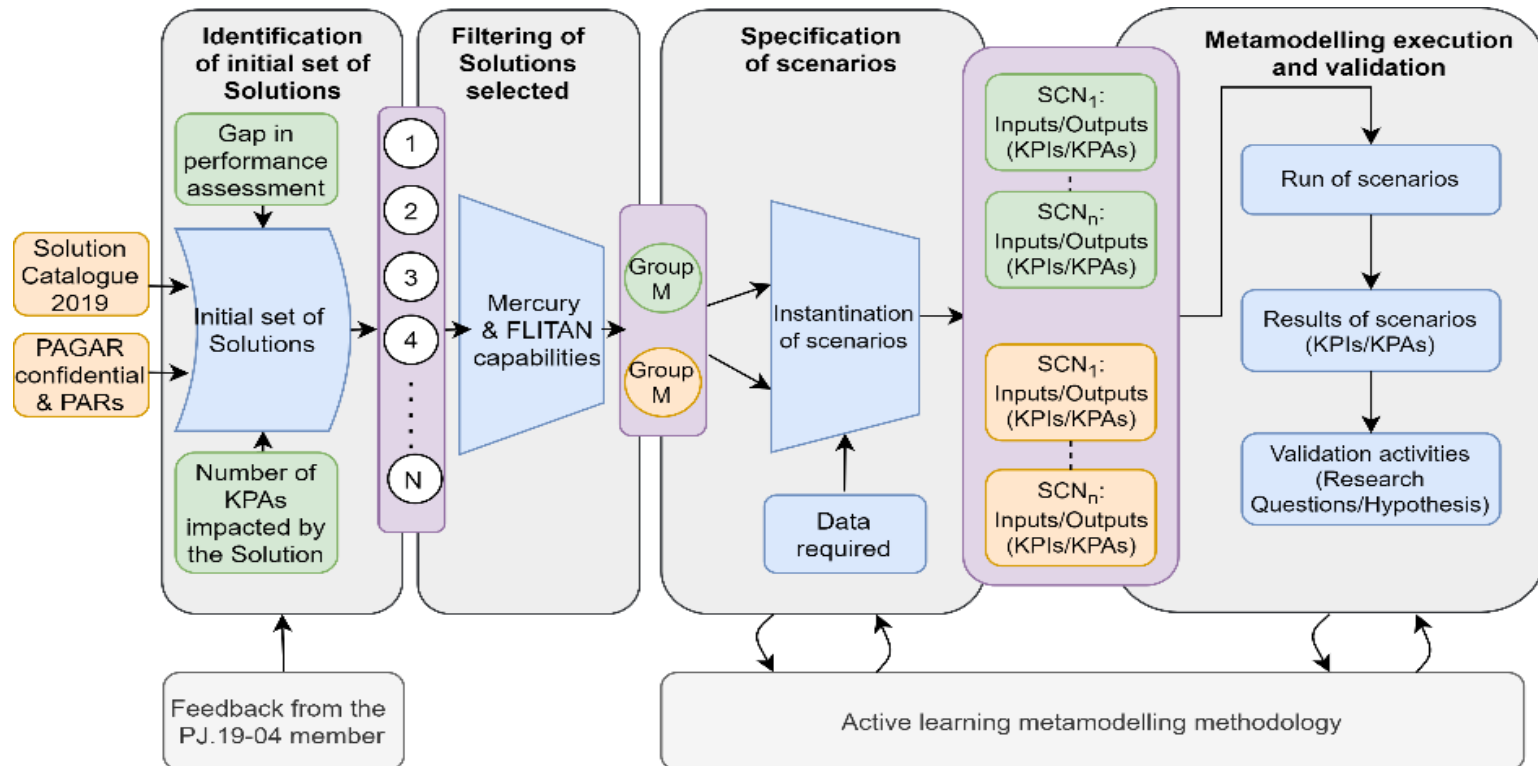
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# Preliminary Specification of Cases Studies – General Approach

## Top-down Approach



## Bottom-up Approach

# Preliminary Specification of Cases Studies – Top-down Approach

Solutions at V3 in SESAR 2020 Wave 1										
Sol.	FEFF	APT CAP	TMA CAP	ENR CAP	PRD	PUN	ATCO	TECH	SAF	HP
PJ.01-06	ok								Yes	Yes
PJ.02-01	H-	H+			ok				Yes	Yes
PJ.02-02	ok	M-					ok		Yes	Yes
PJ.02-03	ok	H+					ok		Yes	Yes
PJ.02-05	ok				ok				Yes	Yes
PJ.02-08	ok	H+	H-		H-	ok			Yes	Yes
PJ.03a-04	ok				M-	M-	ok		Yes	Yes
PJ.03b-05									Yes	Yes
PJ.05-02							M+		Yes	Yes
PJ.06-01	H-				ok				Yes	Yes
PJ.10-01a	M-				ok		M-		Yes	Yes
PJ.10-02a	M-		ok		H+	ok	H-		Yes	Yes
PJ.11-A1									N/A	Yes
PJ.14-02-02									N/A	N/A
PJ.14-02-06									N/A	N/A
PJ.14-03-04									N/A	N/A
PJ.15-01								ok	N/A	N/A
PJ.15-02								ok	N/A	N/A
PJ.15-10								ok	N/A	N/A
PJ.15-11								ok	N/A	N/A
PJ.16-03								ok	N/A	N/A
PJ.17-01									N/A	N/A
PJ.18-02b	ok		M-	M-			ok		N/A	N/A
PJ.18-02c	ok		ok	M-	ok	ok	ok		Yes	N/A
18-04a					ok				N/A	N/A
18-04b	ok								N/A	N/A
06a	M-								N/A	N/A

Solutions non-fully V3										
Sol.	FEFF	APT CAP	TMA CAP	ENR CAP	PRD	PUN	ATCO	TECH	SAF	HP
PJ.01-01	M-		H-		M-	M-			Yes	Yes
PJ.01-02	H-		H+		H-	H-	M-		Yes	Yes
PJ.01-03A			ok		ok		ok		Yes	Yes
PJ.01-03B	M-				ok		ok		N/A	Yes
PJ.01-03C							ok		N/A	No info
PJ.01-05	ok	M+	M+		M+		ok		N/A	Yes
PJ.01-07	ok								N/A	N/A
PJ.02-06	ok				ok				No	No info
PJ.02-11	ok		ok		M-		ok		Yes	Yes
PJ.03a-01	ok				M-		ok		Yes	Yes
PJ.03a-03	ok								N/A	N/A
PJ.03a-09									Yes	Yes
PJ.03b-01									Yes	Yes
PJ.03b-03									Yes	Yes
PJ.03b-06		ok							Yes	Yes
PJ.04-01	ok		ok		M-	ok			No	No info
PJ.04-02	ok				ok	H-			Yes	No info
PJ.05-03							M+	H-	Yes	Yes
PJ.05-05									N/A	N/A
PJ.06-02	ok				ok				Yes	Yes
PJ.07-01	M-				M-	ok			Yes	Yes
PJ.07-02						M-			Yes	Yes
PJ.07-03				ok	ok				Yes	Yes
PJ.08-01	ok			H+	ok		ok		Yes	Yes
PJ.08-02	ok			H+	ok		ok		N/A	N/A
PJ.09-01									Yes	No info
PJ.09-02	ok		M-	H+	M-	ok	M+		Yes	Yes
PJ.09-03	ok		H-	H+	M+	M+	M+		Yes	Yes
PJ.10-01b	M-		ok	M-	ok		H-		Yes	Yes
PJ.10-01c	H-				ok		ok		Yes	Yes
PJ.10-02b	ok		H+	H+	ok		M+		Yes	Yes
PJ.10-05									No	Yes
PJ.10-06							M+		Yes	Yes
PJ.11-A2									Yes	Yes
PJ.11-A3									N/A	Yes
PJ.11-A4									Yes	Yes
PJ.11-G1									Yes	Yes



The number of KPAs impacted by the specific solutions

The magnitude of remaining gap - the solutions classified as "H-" and "M-"

# Preliminary Selection of Case Studies: Bottom-up Approach

PJ.01-01

PJ.01-02

PJ.07-01

PJ.07-02

PJ.08-01

PJ.08-02

PJ.09-02

PJ.09-03

PJ.10-01b

PJ.02-08

PJ.06-01

PJ.10-02a

Mercury  
Capabilities

FLITAN  
Capabilities

# Preliminary Selection of Case Studies: Bottom-up Approach

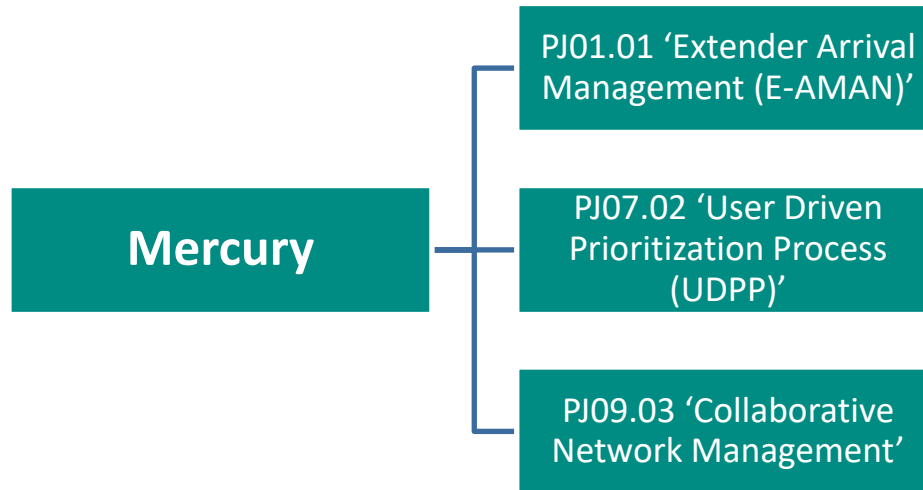
PJ.01-01	PJ.01-02	PJ.07-01	PJ.07-02
PJ.08-01	PJ.08-02	PJ.09-02	PJ.09-03
PJ.10-01b	PJ.02-08	PJ.06-01	PJ.10-02a
	Mercury Capabilities	FLITAN Capabilities	

# Preliminary Selection of Case Studies: Bottom-up Approach

PJ.01-01	PJ.01-02	PJ.07-01	PJ.07-02
PJ.08-01	PJ.08-02	PJ.09-02	PJ.09-03
PJ.10-01b	PJ.02-08	PJ.06-01	PJ.10-02a
	Mercury Capabilities	FLITAN Capabilities	

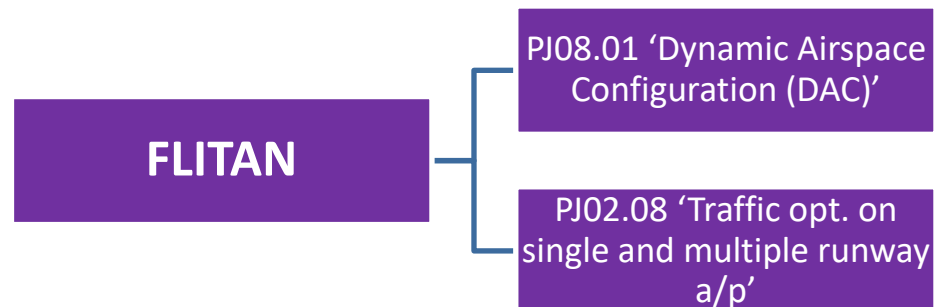


# Preliminary Selection of Case Studies



## Research Questions:

Test if unified constraint management, (constraints created by the UDPP slot allocation, by the E-AMAN tactical slot allocation etc) is more efficient than decentralised decision-making processes, when solutions like UDPP and E-AMAN are not synchronised (i.e. constraints are not shared).



## Research Questions:

What are the overall benefits in terms of capacity, flight efficiency and punctuality of a holistic integration of both en-route and airport operations?



## Application of Active Learning: NOSTROMO Methodology

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# Active Learning with Simulators



**Main problem:** How can we use a simulator to search for policy-relevant values?

- Systematic exploration is **exhausting**
- **Computational hindrances** strongly limit comprehensive scenario analysis

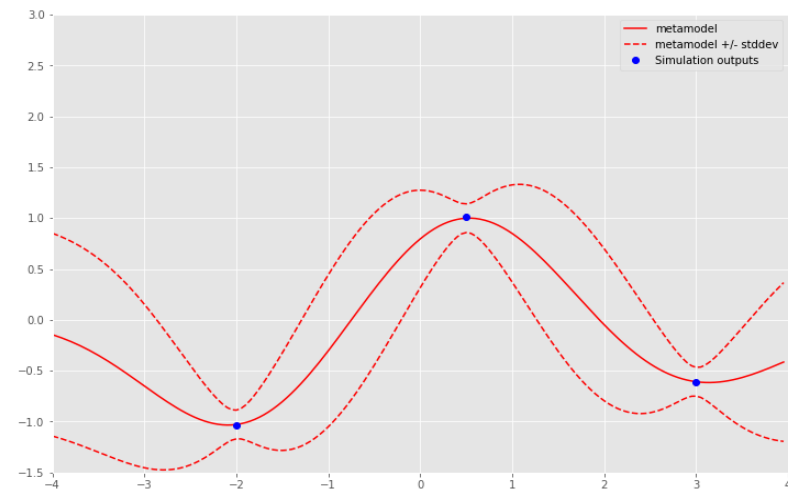
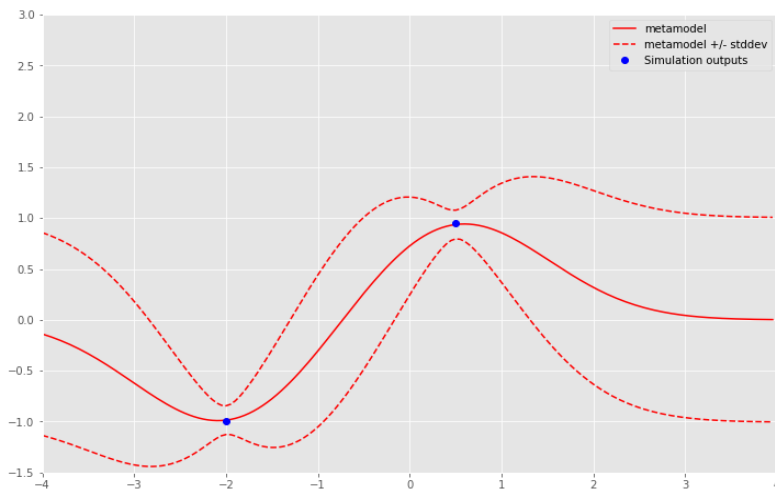
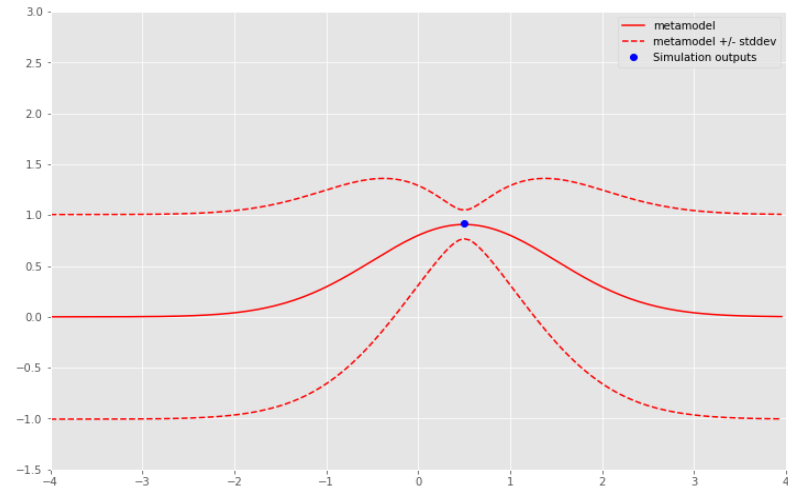
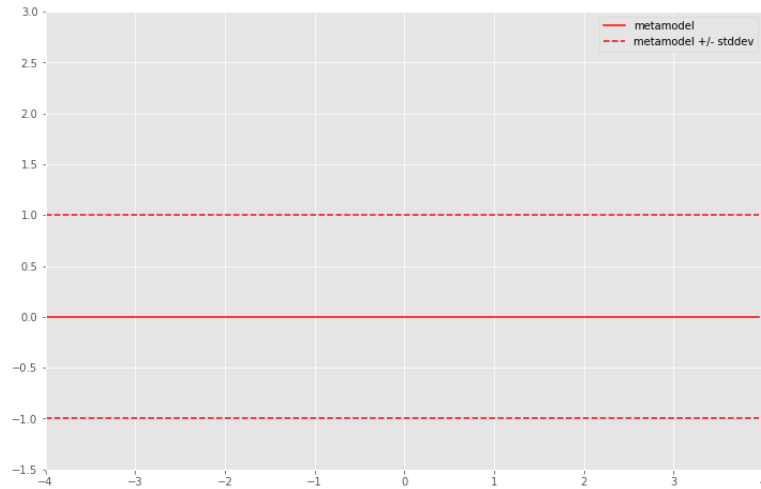
**Aims:**

- Avoid **redundant simulation runs**
- Efficient **guidance of simulation analysis**
- **Predict** simulation output values given any input

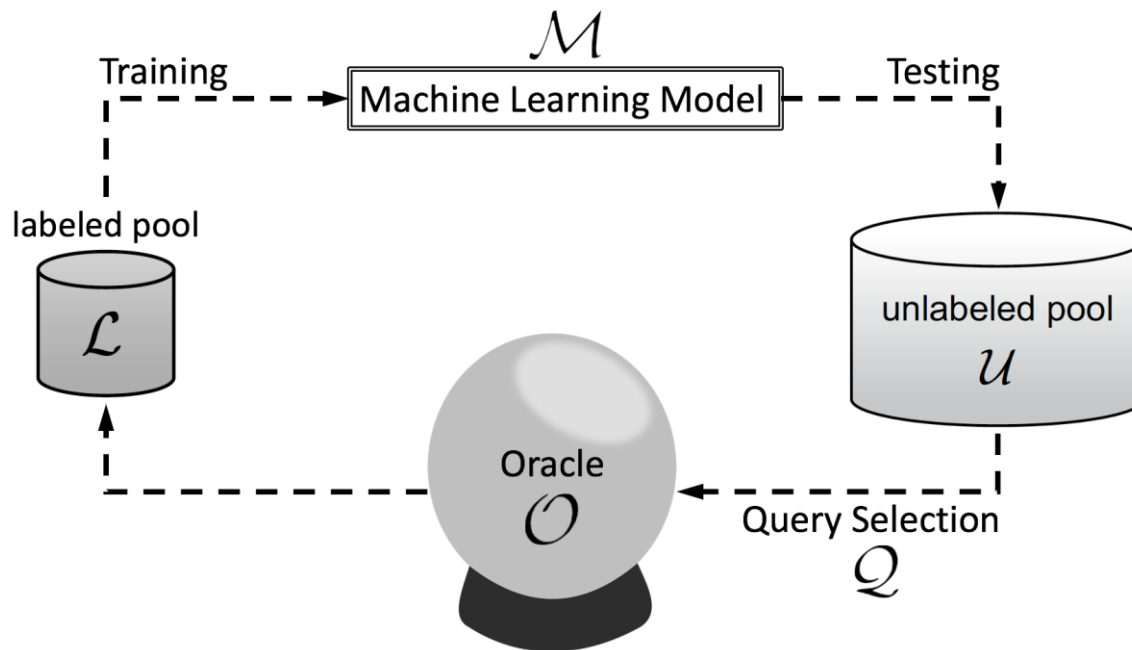
**Proposed solution:**

- **Integration of** active learning and simulation metamodeling
- **Active learning** → achieve greater performance with fewer data points
- **Simulation Metamodeling** → approximate the simulation model by a simpler and faster *black box*

# Active Learning in general

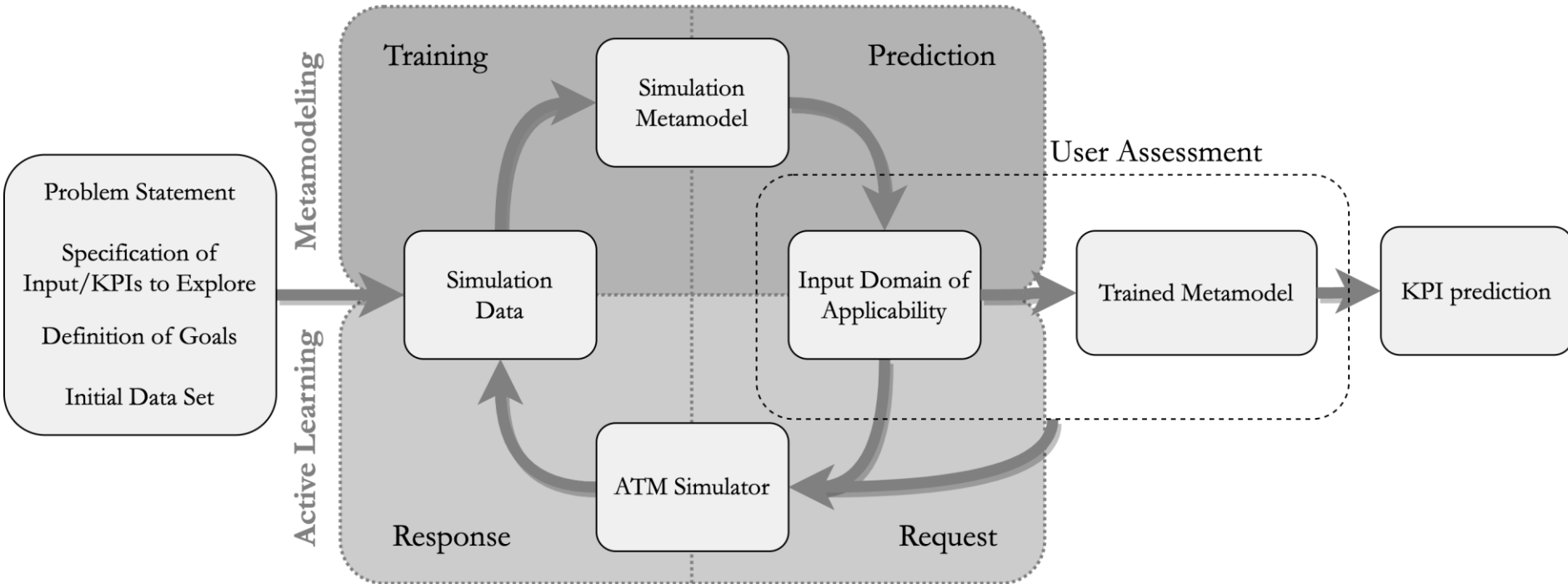


# Active Learning in general



- High predictive performance with fewer data points; iterative training/learning process [Angluin (1988), Cohn et al. (1994), Freund (1997)].
- Gaussian Process (GP) framework [Rasmussen and Williams (2005)] allows for an intuitive way of developing active learning algorithms.

# Active Learning in NOSTROMO



# Active Learning: important notes

## Initial data

Should be representative enough, thus  
initial simulation effort not entirely  
avoidable

## Domain knowledge

Expertise supervision recommended

## Retraining of metamodel

Might be required depending on expert's  
feedback

## Trade-off speed VS accuracy

Trade-off constantly tracked and adjusted  
according to objectives

## Approximate nature

Essential to keep in mind the approximate nature when drawing conclusions and  
improving model

# Active Learning: latest results

Test case: Mercury with 1000 flights

**TABLE 1 Summary description of the Mercury input/output simulation variables used for metamodeling.**

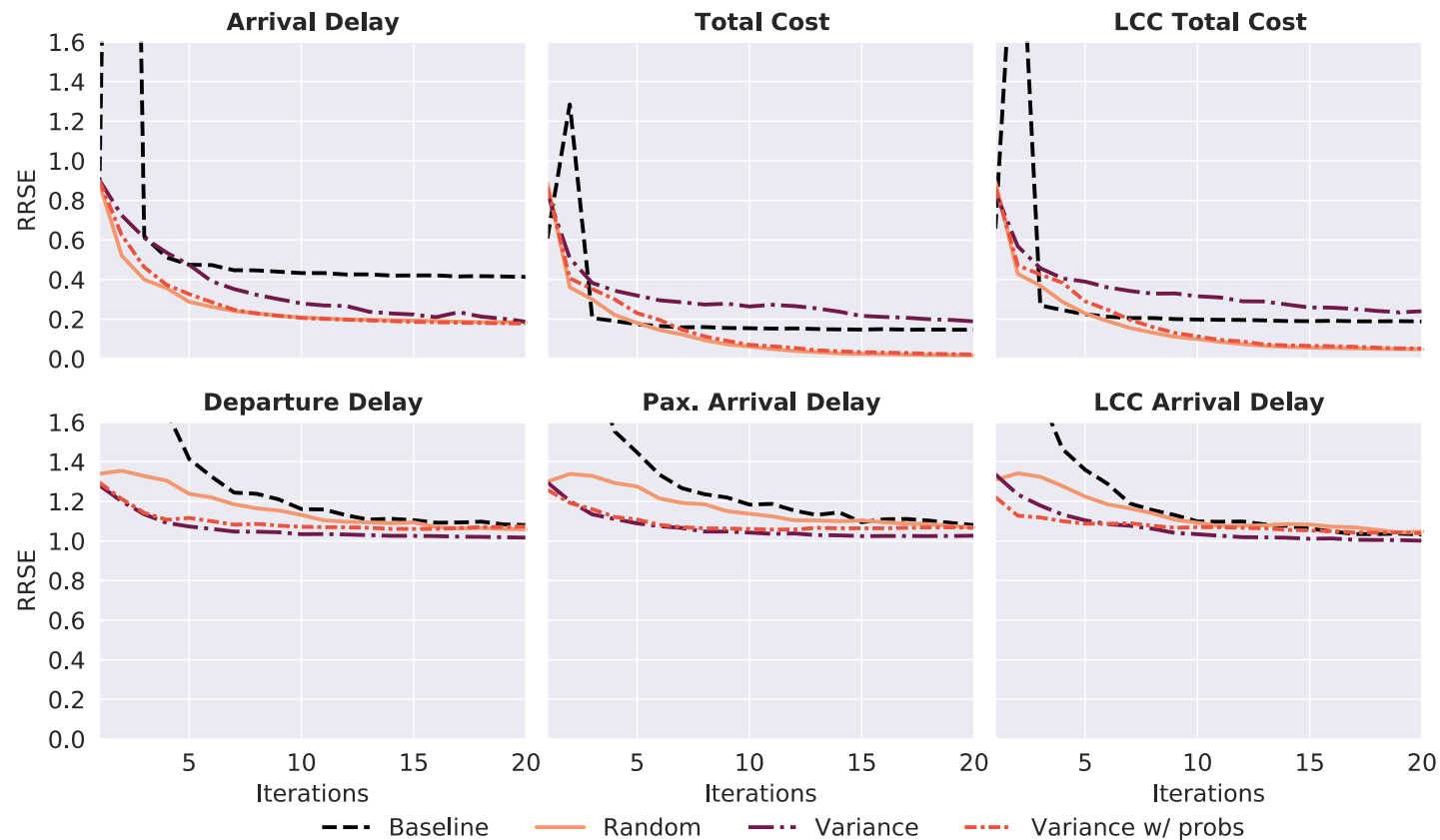
	var	name	description	values
Inputs	$x_1$	compensation_magnitude_long1	Compensation between first and second thresholds for long-haul passengers in euros (€)	[0, 500, 1000, ..., 5000]
	$x_2$	first_compensation_threshold	Threshold of arrival time after which the passengers receive a compensation in minutes	[0, 60, 120, ..., 480]
	$x_3$	fuel_price	Price per kilogram of fuel in euros (€)	[0, 0.5, 1, ..., 5]
Outputs	$y_1$	arrival_delay_min_mean	Average arrival delay per flight in minutes	real-valued
	$y_2$	departure_delay_min_mean	Average departure delay per flight in minutes	real-valued
	$y_3$	total_cost_mean	Average total cost per flight operation in euros (€)	real-valued, positive
	$y_4$	pax_tot_arrival_delay_mean	Average total arrival delay per passenger in minutes	real-valued, positive
	$y_5$	lcc_arrival_delay_min_mean	Average arrival delay per flight for low cost carriers in minutes	real-valued
	$y_6$	lcc_total_cost_mean	Average total cost per flight for low cost carriers in euros (€)	real-value, positive



# Active Learning: latest results

Baseline: Quadratic regression and static sampling (LHS)

Proposal: Active learning with Gaussian Process (3 different strategies)



# Active Learning: latest results

Predictions for *arrival delay* after different number of iterations.

0 iterations:

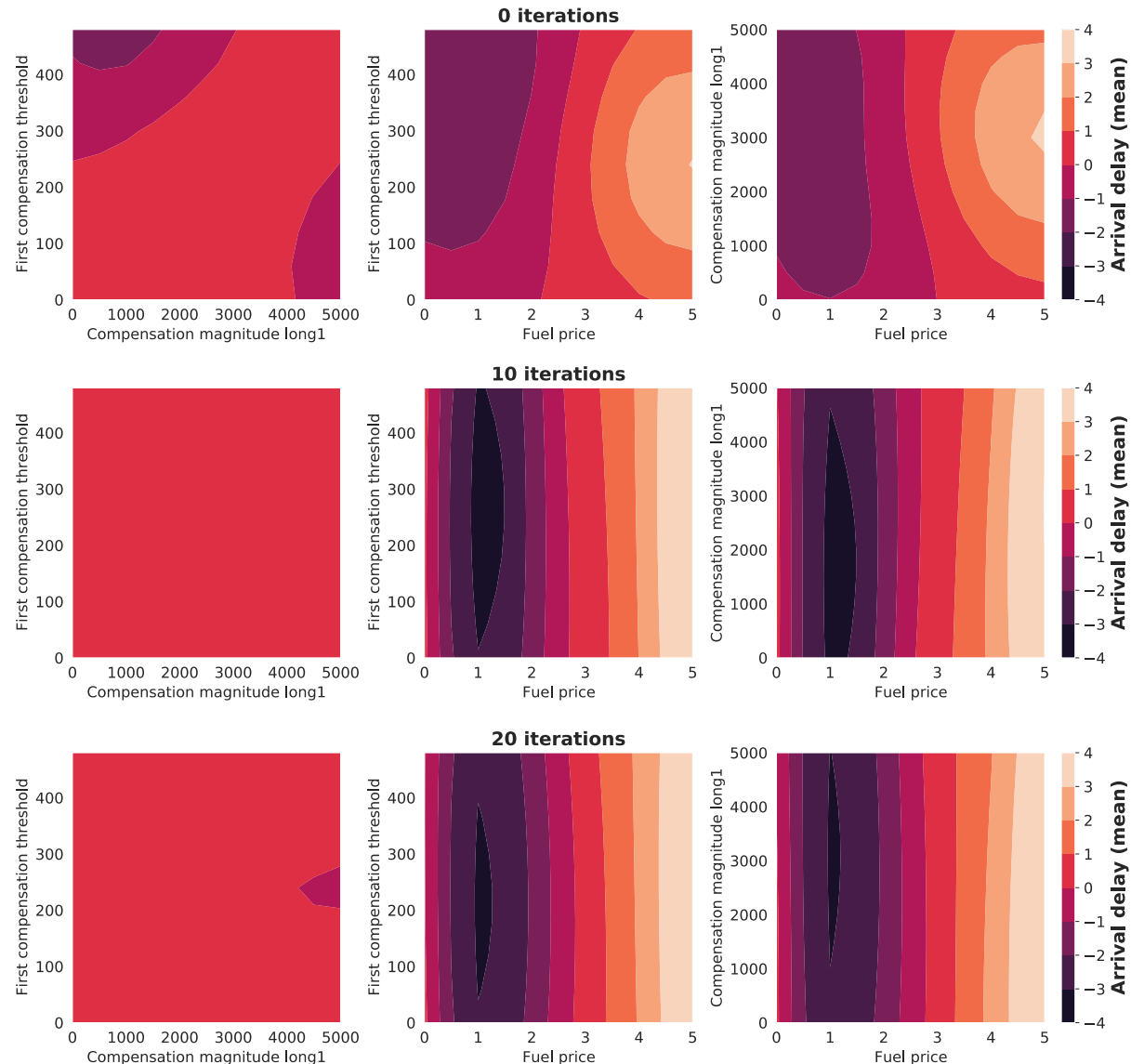
With the initial data, only a vague signal detected.

10 iterations:

Clear trend observed

20 iterations:

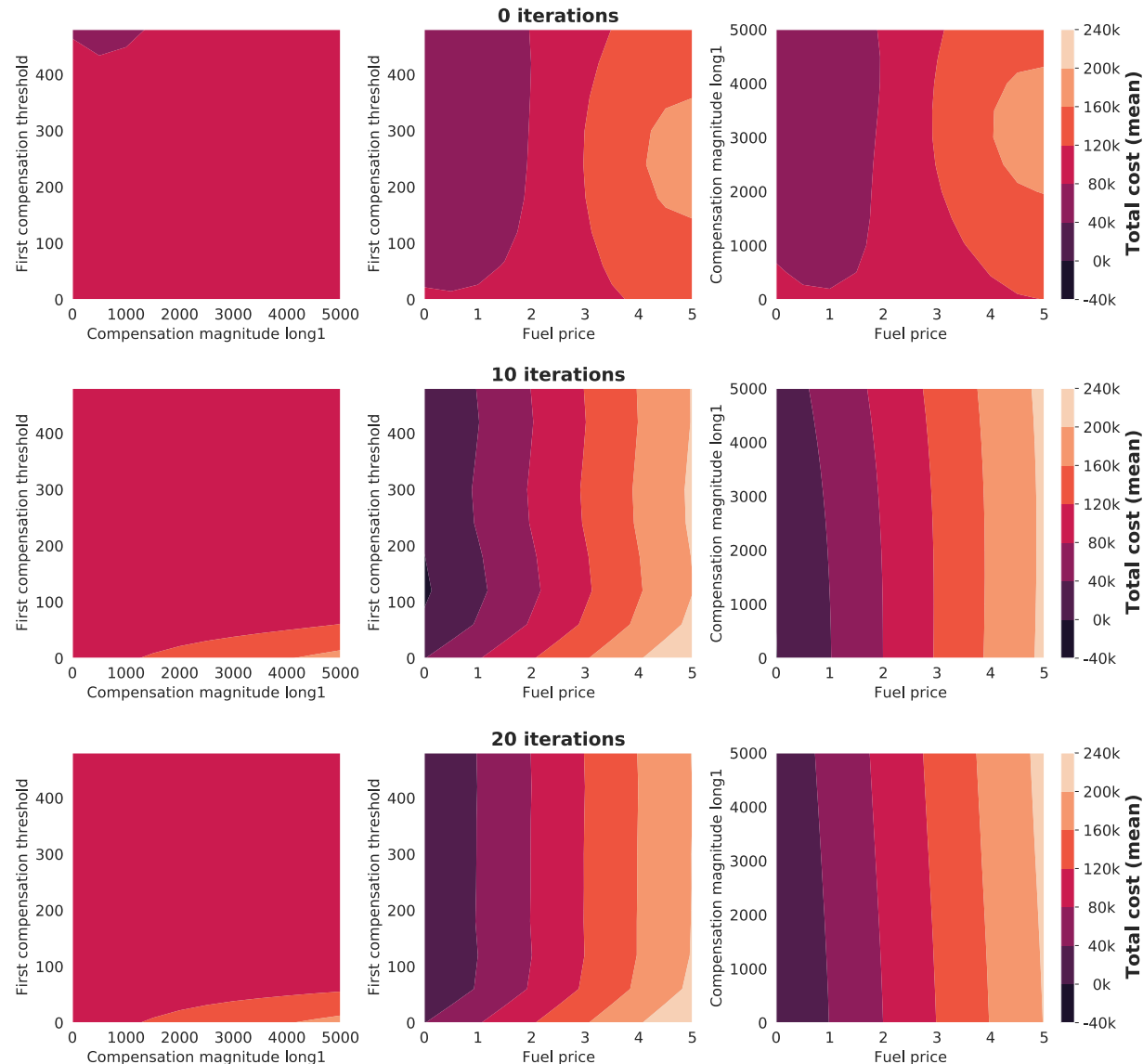
Only minor improvement with the extra iterations.



# Active Learning: latest results

The predictions for *total cost* after different number of iterations.

Same conclusions as before.





## Next Steps for NOSTROMO

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EUROPEAN UNION



EUROCONTROL



# What are we going to get at the end of the Project?

## OBJ#1 - Metamodeling Methodology

Methodology applied to the case studies and guidelines to apply it to other concepts.

## OBJ#2 - Metamodels Implementation

Architecture to apply the methodology to the NOSTROMO case studies with the ability of integer new simulators to prove other concepts.

## OBJ#3 - Visualisation

Visual dashboard to support the decision-making and to explore the trade-offs between KPAs/KPIs.

## OBJ#4 - Evaluation and Benchmarking

Evidences of the methodology feasibility and a benchmark with existing ones.

**New approach to ATM performance modelling**

Foundation for SESAR  
2020 PJ19.04 Wave3  
project



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Thank you very much  
for your attention!

Founding Members

