



Advanced Statistical Signal Processing for Next Generation Trajectory Prediction

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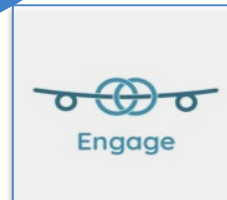
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January 25, 2021

The 3rd workshop on Thematic Challenge 2 (TC2)
(Virtual)



Founding Members



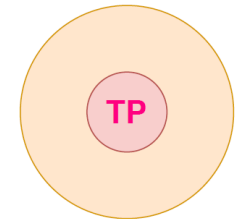
Introduction

Accurate and reliable TP:

- Next generation of **onboard** and **ground-board** DSTs:
- Enhanced safety net:

The aim of this PhD:

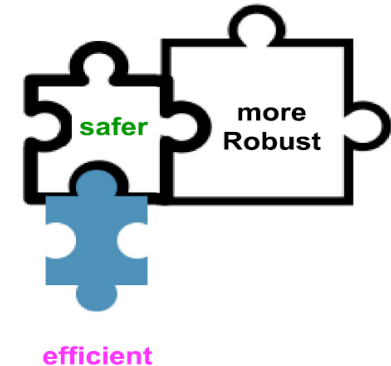
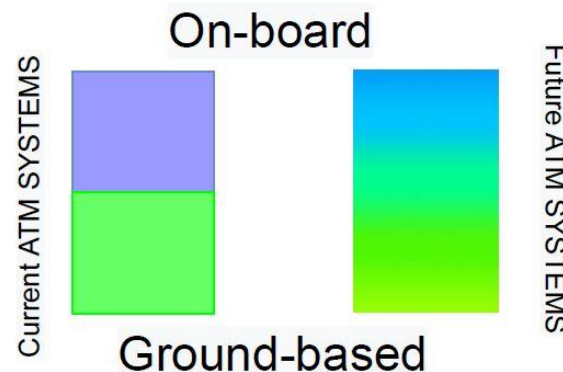
New **SSP** approach to improve **TP** in new generation **ATM** systems



Next Generation
ATM Systems

TP for the flight **execution phase**.

Onboard TP
Ground-based TP



* *Trajectory Prediction (TP)*, * *Decision Support Tools (DST)*, * *Statistical Signal Processing (SSP)*, * *Air Traffic Management (ATM)*, * *Trajectory Based Operations (TBO)*, * *Single European Sky ATM Research (SESAR)*, * *Next Generation Air Transportation System (NexGen)*,

3rd workshop on Thematic Challenge 2 (TC2) – 25th January 2021 – “Statistical Signal Processing for Next Generation Trajectory Prediction”

– Homeyra Khaledian

PhD Research Objectives

Towards **Robust TP** Solutions.

- **O1: Probabilistic characterization** of the **TP** problem at hand, and formal analysis on the limitations of standard filtering techniques for TP (i.e., impact of a **misspecified** system).
- **O2: Robustification** of the current filtering techniques and development of **new robust approaches for TP** (i.e., relying on **linearly constrained** filtering, using **covariance estimation** techniques or advanced **Bayesian filtering** solutions).

From Single to **Multiple Aircraft TP**.

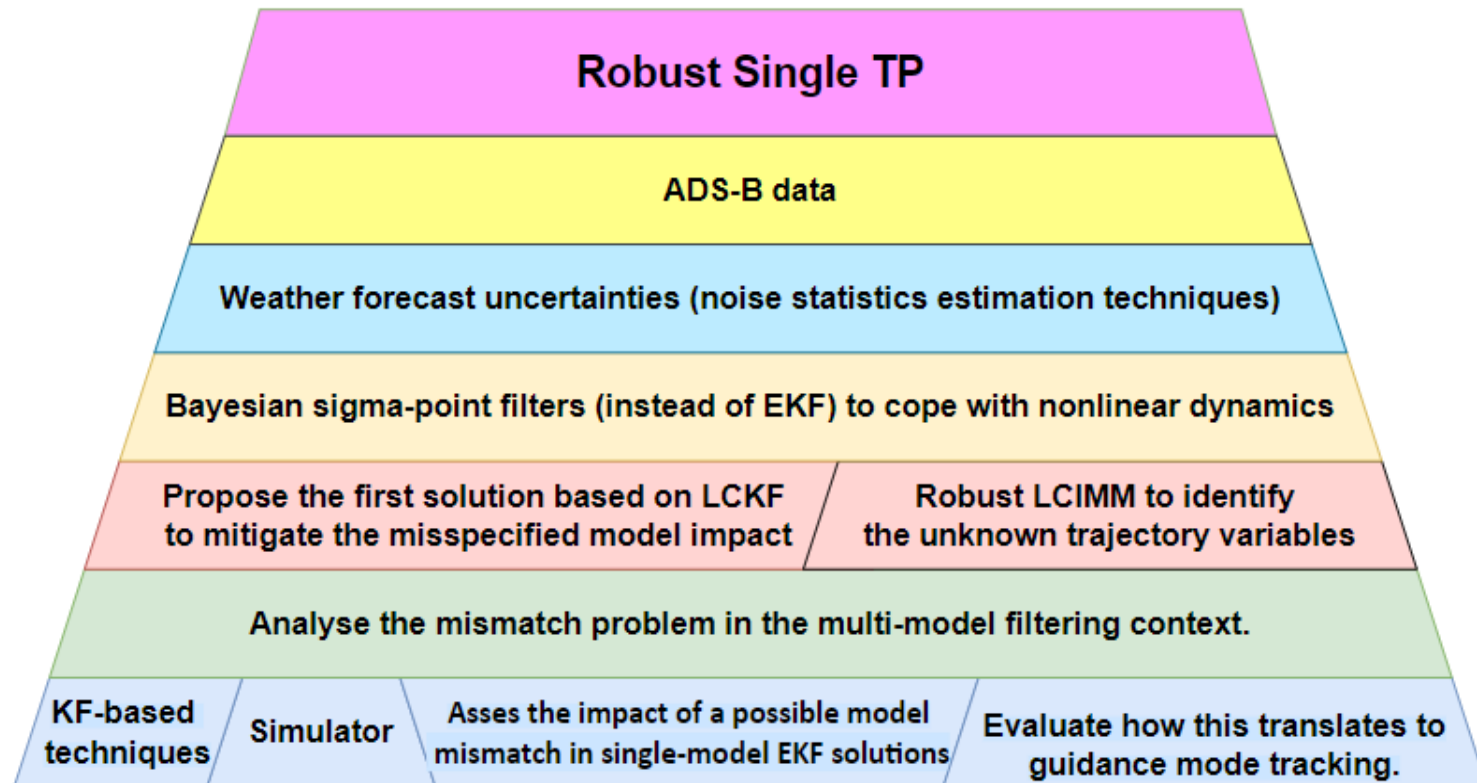
- **O3:** Extension of the **robust filtering** approaches developed in O1 to **multiple aircraft TP**.

From **Centralized** to **Cooperative** Processing.

- **O4:** Development of **distributed or cooperative robust filtering** techniques, as an extension of the methodologies developed in O1 to enable **self-separation**.

* *Trajectory Prediction (TP)*, * *Objective (O)*,

Towards Robust TP Solutions (**O1** and **O2**):

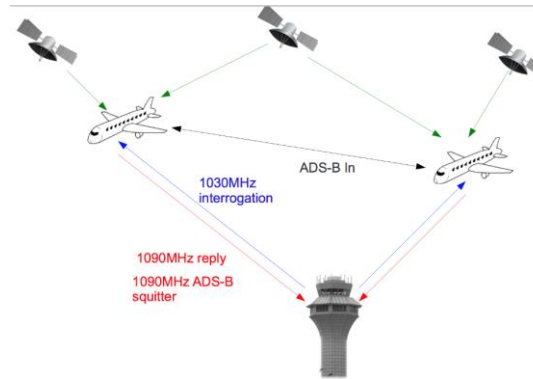
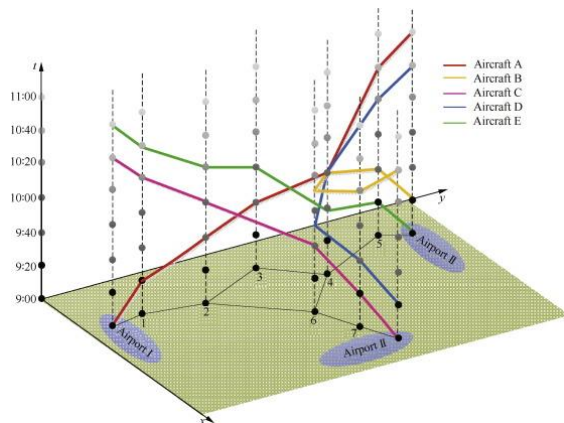


* *Trajectory Prediction (TP)*, * *Extended Kalman Filter(EKF)*, * *Automatic Dependent Surveillance Broadcast (ADS-B)*, * *Linear Constraints Kalman Filter (LCKF)*, * *Linear Constraints Interacting Multiple-model (LCIMM)*,

Applications

Case studies to appraise the impact of the **proposed methods** in applications which demand **TP**:

- Improving the **MTCD-like** systems or more general **CDR** algorithms.
- Improving **self-separation** algorithms.
- Multi aircraft CD.**



* *Trajectory Prediction (TP)*, * *Medium Term Conflict Detection (MTCD)*,
* *Conflict Detection and Resolution (CDR)*, * *conflict detection (CD)*



Thank you for your attention

3rd workshop on Thematic Challenge 2 (TC2) 2021 (Virtual)

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